

## iSCAPE Final Event



iSCAPE Sensor Development IAAC - Fablab Barcelona

> Dublin, Ireland 8 November 2019



## **ISCAPE SENSORS**

Óscar González

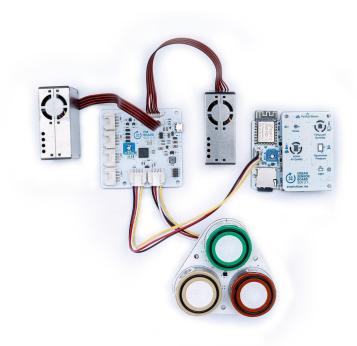
Calibration and sensor development



### iSCAPE Sensor Development

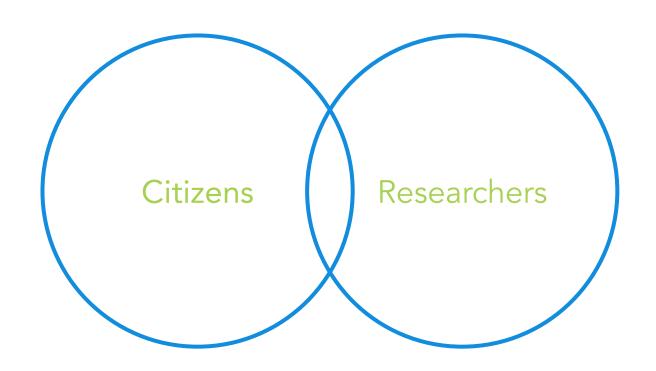
#### Content:

- From Citizen to Researchers
- Our journey of sensor development
- Where we are today



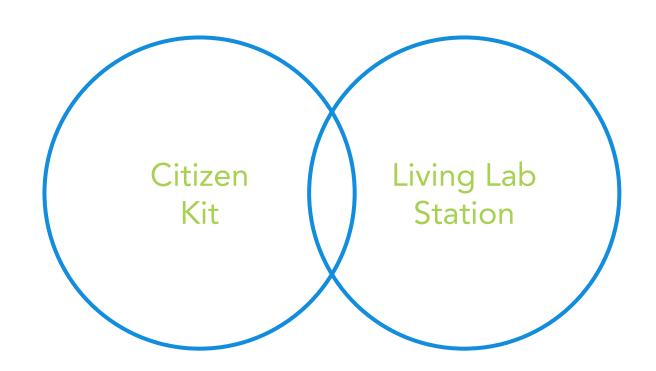














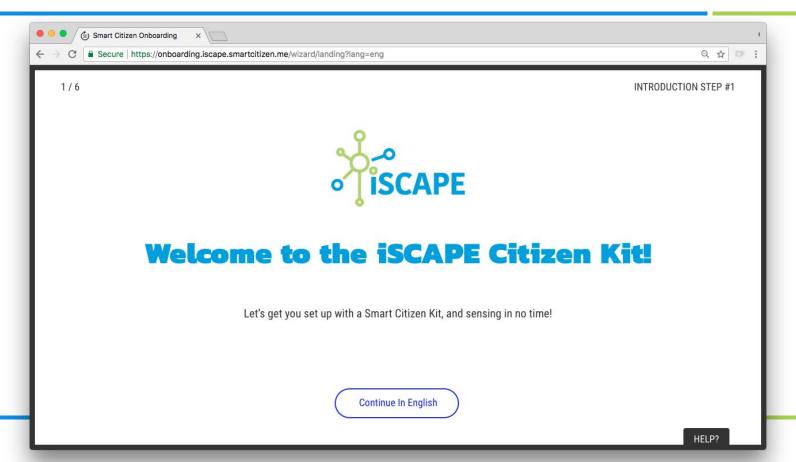


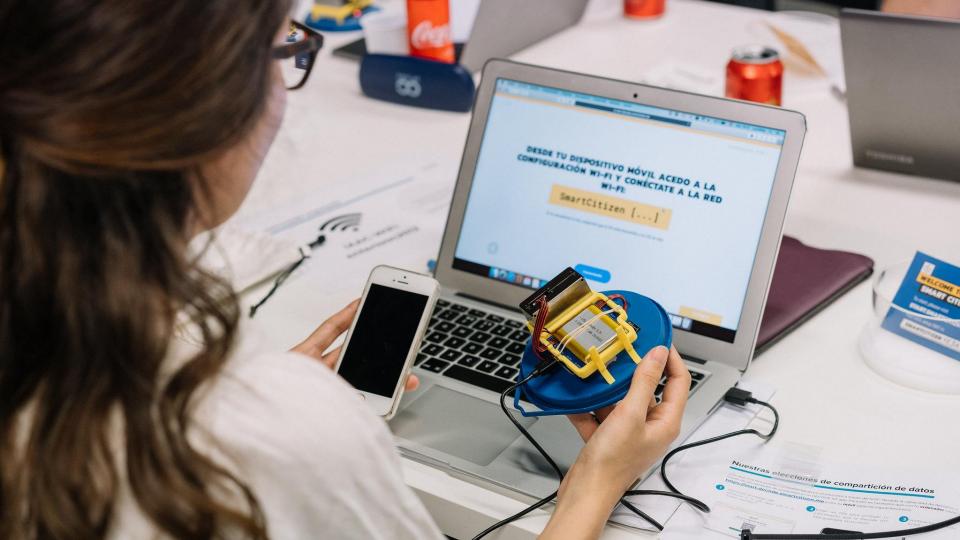
#### <u>Citizen Science</u> is about:

- Raising awareness
- Engagement
- Learning experience
- Variety of use cases
- Transparency



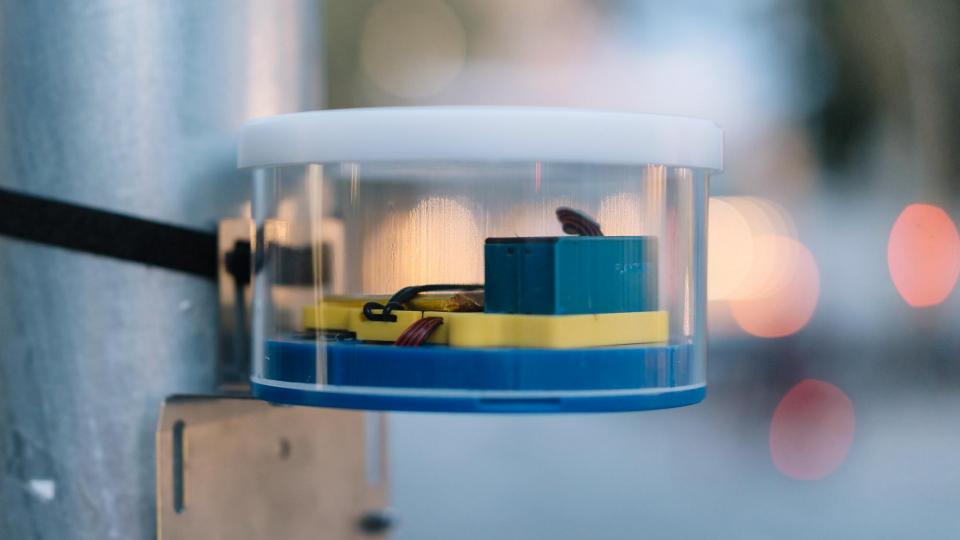


















- Raising awareness
- Engagement
- Learning experience
- Variety of use cases
- Transparency

- Easy to come aboard
- Data ownership
- Flexibility
- Openness
- Sense of community

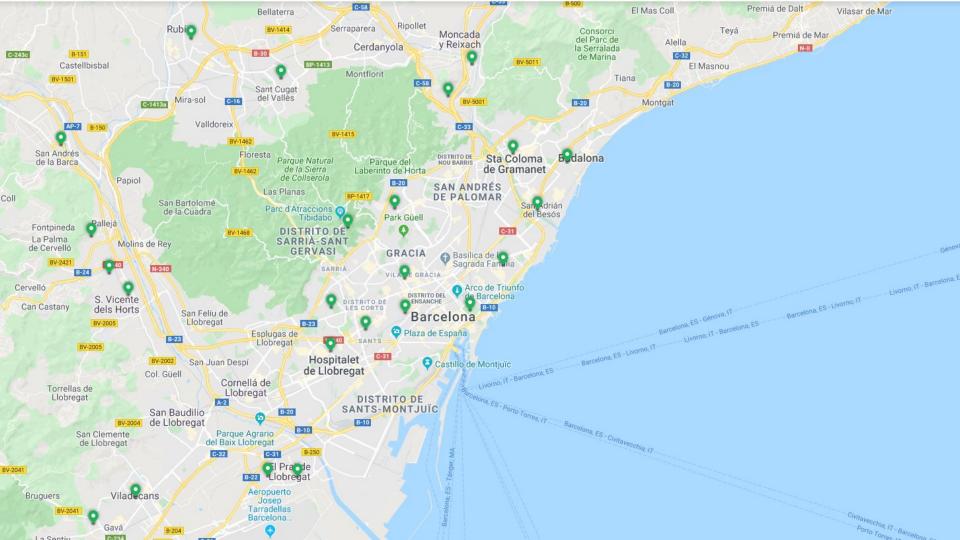




#### Researchers need:

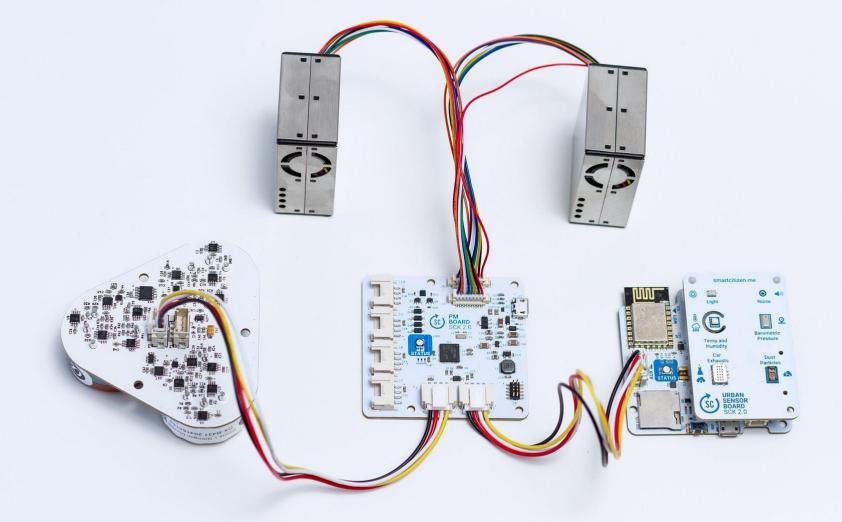
- Scientifically validated instrumentation
- Reproducibility
- Openness (sometimes they don't know that)
- Cost efficient
- Autonomy



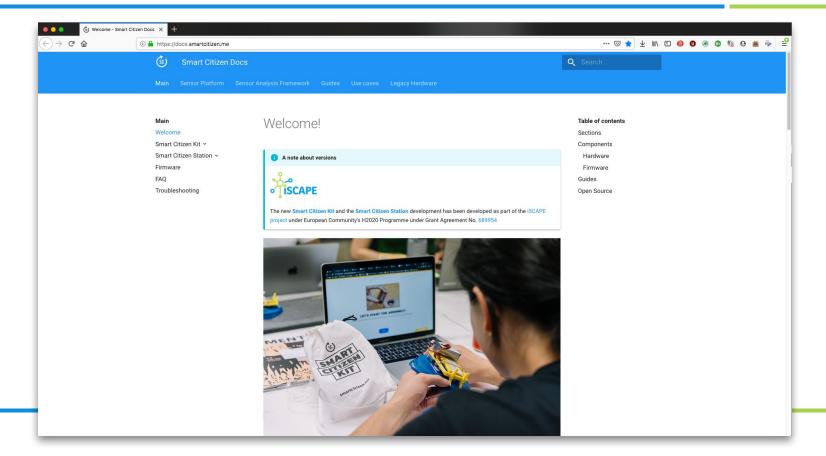






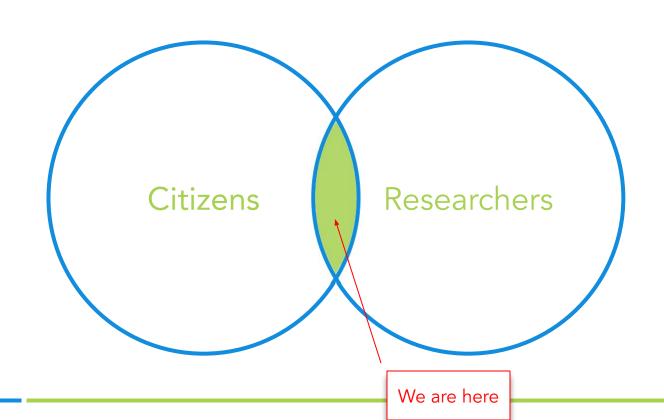




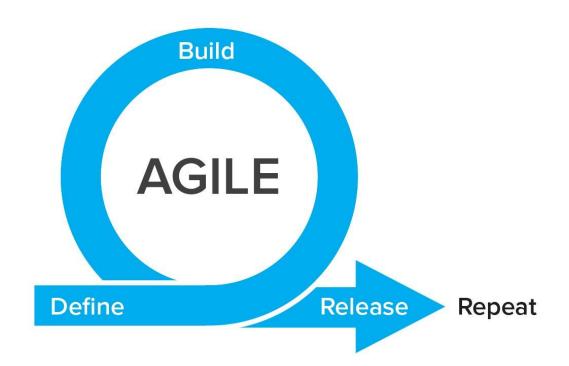








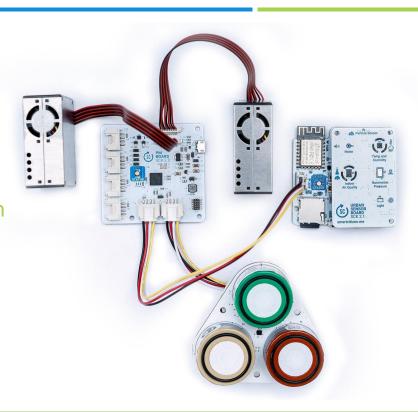






#### Our approach:

- Iterative development
- Develop, test, improve, and do it again
- Flexible
- Modular
- Open













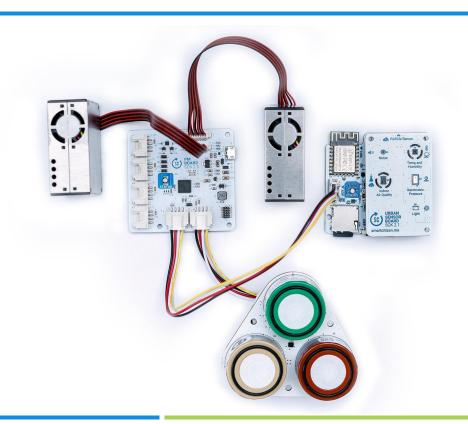
Measurement	Units	Sensors
Air temperature	°C	Sensirion SHT-31
Relative Humidity	% REL	Sensirion SHT-31
Noise level	dBA	Invensense ICS-434342
Ambient light	Lux	Rohm BH1721FVC
Barometric pressure	Pa	NXP MPL3115A26
Equivalent Carbon Dioxide	ppm	AMS CCS811
Volatile Organic Compounds	ppb	AMS CCS811





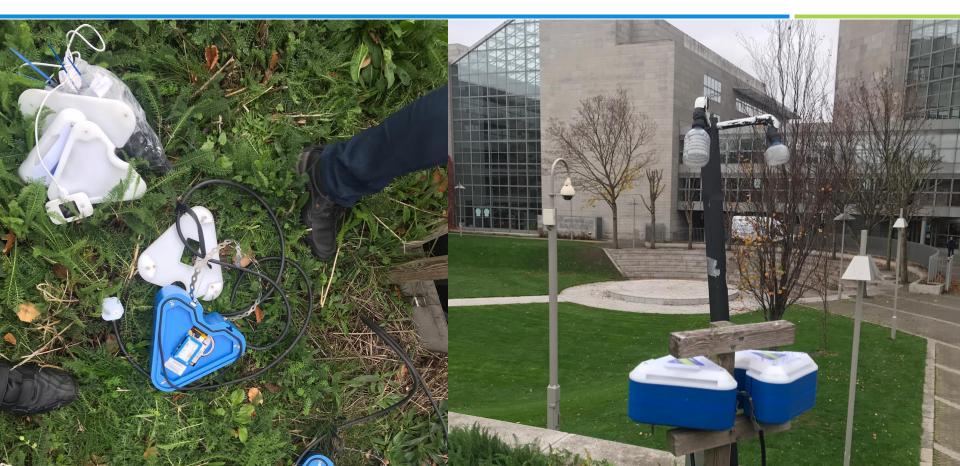






Measurement	Units	Sensor	Component
Carbon Monoxide	ppm	Alphasense CO-B4	Gas Sensor Pro Board
Nitrogen Dioxide	ppb	Alphasense NO2-B43F	Gas Sensor Pro Board
Ozone	ppb	Alphasense OX-B431	Gas Sensor Pro Board
Gases Board Temperature	°C	Sensirion SHT-31	Gas Sensor Pro Board
Gases Board Rel. Humidity	% REL	Sensirion SHT-31	Gas Sensor Pro Board
PM 1	μg/m3	Plantower PMS5003 Dual System	PM Sensors Board
PM 2.5	μg/m3	Plantower PMS5003 Dual System	PM Sensors Board
PM 10	μg/m3	Plantower PMS5003 Dual System	PM Sensors Board

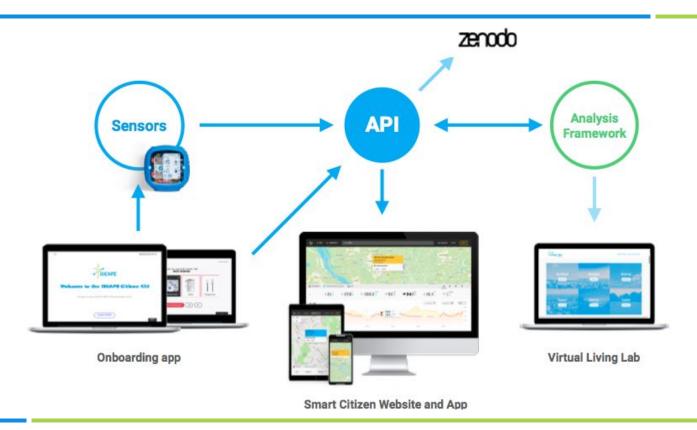














#### The importance of data analysis:

- Low cost sensors are useless without algorithms
- Understand sensor behaviour
- Improve measurements
- Understand how to deploy the sensors

Open framework for sensor data analysis

```
MICS-Analysis-v0.1

    C © localhost 8888/notebooks/MCS-Aratysis-v0.1 joynost

                                                                                                                                  9.0
           JUDY TET MICS-Analysis-v0.1 Last Checkpoint: an hour ago (unsaved changes)
                                                                                                         Trusted / Python 2 O.
                       Correlation
              In (131) def redres(b):
                            mergedData = pd.merge(readings[A kit.value].loc[:,(A mensors.value,)], readings[B kit.value
                            clear output()
                            #jointplod
                            df = pd.DataFrame()
                            A = A sensors.value + ' - ' + A kit.value
                            3 - 3 sensors.value + ' - ' + 3 kit.value
                            df[A] = mergedData.iloc[:,0]
                            df[B] = mergedData.iloc[:,1]
                            sns.set(font scale=1.3)
                            sns.jointplot(A, B, data-df, kind-"rog", color-"b", size-12, scatter kws-("s": 80));
                            pearsonCorr = list(df.corr('pearson')(list(df.columns)(0)))(-1)
                            print ('Pearson correlation coefficients ' * str(pearsonCorr))
                            print ('Coefficient of determination R') ' + str(pearsonCorr'pearsonCorr))
                            fig = plt.figure(figsize=(15, 15))
                            ax = fig.add_subplot(2,1,1)
                            ax.plot(df, linewidth=1, alpha=0.9)
                            ax.legend(list(df.columns))
                            # Rolling correlation
                            roll = mergedData.iloc[:,0].rolling(:2).corr(mergedData.iloc[:,1])
                            ax1 = fig.add_subplot(2,1,2,sharex=ax)
                            ax1.plot(roll, linewidth=2, alpha=0.9)
                            plt.ylim([-1.1,1.1])
```



# Where we are today



### Where we are today







smartcitizen.me





Your kit's setup WIFI is:

SMARTCITIZEN 2883

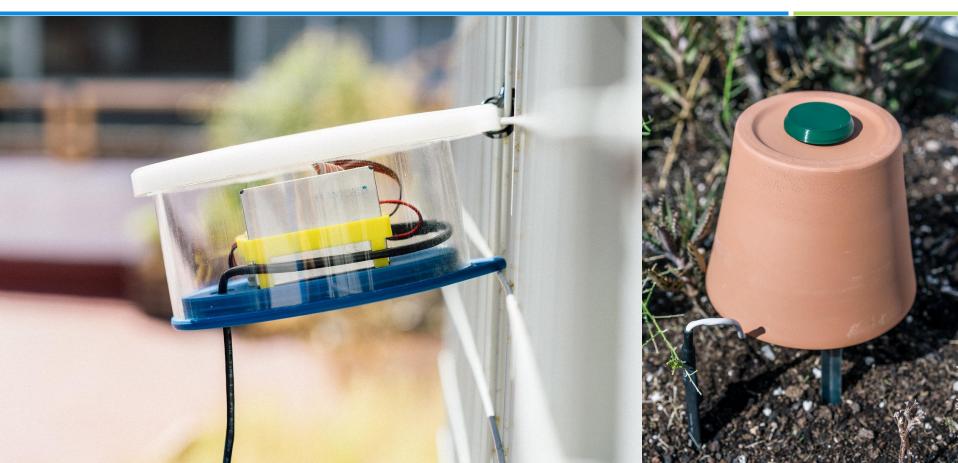


























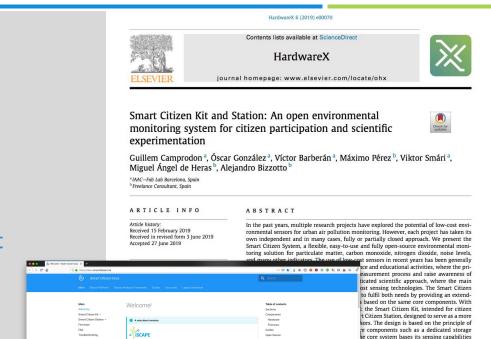
### Where we are today

to provide a robust framework for environything open, from the hardware to the softalgorithms, we hope others might find it em to focus on their project particular needs ound-up.

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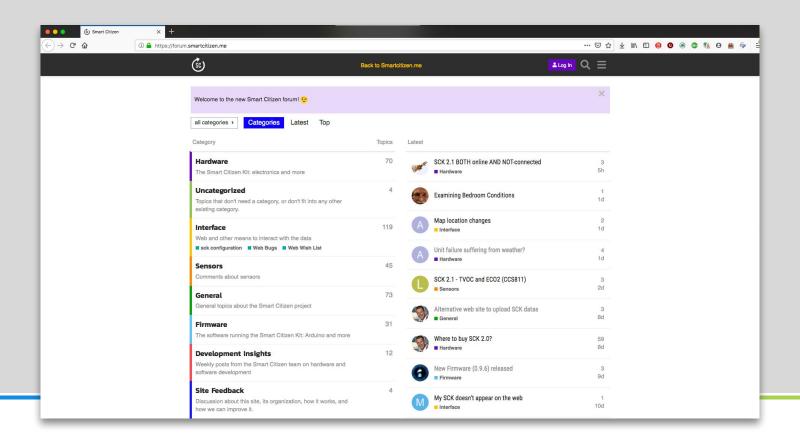
#### **Dissemination**:

- Special Issue on Open-Hardware for Environmental Sensing and Instruments
- Evaluation of particle
   size-selectivity of optical low-cost
   particulate matter sensors
- Online web documentation





### Where we are today





# Thank you